Predicting ICME Signatures at L1 with a Data-Constrained Physical Model

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Predicting ICME Structures at L1

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- Observations and Events
- Models and Fittings
- Prediction Results

5 Discussion



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Introduction

- Coronal Mass Ejections (CMEs) are a significant driver of space weather at the Earth
- An accurate prediction of the arrival of CMEs can help mitigate the harmful consequences associated with a CME
- Currently, the standard of prediction is on the order of about 6 hours Colaninno et al. (2013); Gopalswamy et al. (2013); Möstl et al. (2014); Vršnak et al. (2014)

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Our Model

- We present a modified drag-based empirical model to accurately predict the arrival of ICME structures at the L1 point
- For a 7 event sample, we are able to predict arrivals within 4 hours for separate ICME signatures
 - Ejecta- Eruptive material from the corona, likely a flux rope.
 - Sheath- Solar wind plasma accumulated as ejecta propagates. The front of the sheath may or may not be a shock

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Event Selection

- Events were initially selected from ACE data
- An automatic detection algorithm identified potential ICMEs
- Manual conformation provided a larger list of events, 7 of which were picked based on quality of observations



Determining In-Situ Signatures

- With complex ejecta, there can be ambiguity in where the flux rope or flux rope-like structure passes the observer
- In a normal MC, it is usually easy to determine the boundaries of the flux rope. For complex events, to remain consistent we focus on plasma-β
- The sheath is generally more obvious



Event List

First	SH Arrival ^b	EJ Arrival ^b	Direction ^c	V_0^c	V_{sw}^d	R_0^e	R _f ^e	AR ^f	Flare ^g	Flare Peak ^g
Measurement ^a				-		-				
04/03/2010 10:24	04/05 08:00	04/05 11:30	E06S26	854.7	512.4	5.5	62.8	11059	B7	04/03 09:54
05/24/2010 14:54	05/28 02:00	05/28 07:00	E28N03	605.7	362.3	4.6	45.0	-	-	-
09/14/2011 00:24	09/17 02:00	09/17 19:00	W20S16	519.5	396.9	5.3	28.1	11289	-	-
07/12/2012 16:54	07/14 17:00	07/15 07:15	W00S09	1492.0	353.7	4.3	76.6	11520	X1	07/12 15:36
09/28/2012 00:24	09/30 23:00	10/01 06:00	E28N17	1230.5	310.4	6.3	74.1	11577	C3	09/28 00:00
10/27/2012 17:24	10/31 15:00	11/01 00:00	E12N12	400.1	289.8	6.2	49.0	-	-	-
03/15/2013 07:24	03/17 15:30	03/18 00:00	W24S07	1220.2	429.3	7.4	37.0	11692	M1	03/15 05:46

Table : a- The time step of the first SECCHI and LASCO images used for GCS fitting. Given the time offsets between the different satellites, the time given refers to the SECCHI observations

b- Sheath and Ejecta arrivals at ACE as manually determined

c- Initial Velocity (km/s) is obtained by performing a fit of the data using the drag based model over all observations

d- Solar wind speed (km/s) is determined by taking an average value of the ACE data preceding the arrival of the sheath signature

e- The measured ejecta height (R_{\odot}) of the first and last point used for fitting

f- Associated Active Region given by tracking CME back to the surface using EUV data. Not all CMEs can be linked with an active region

g- Flare Strength and Peak determined by comparing the EUV observation to X-Ray flux from GOES

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Imaging the Events

- The bulk of the imaging for the events is from SOHO-LASCO and STEREO-SECCHI
- The events are all measured as far as possible. For most this means about half the SECCHI HI-1 FOV
- While the CME is still into the LASCO C2/C3 FOV, the three distinct viewpoints are combined
- This multiple viewpoint imaging allows for a 3-D reconstruction of each event

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Measuring the Fronts



- Height measurements were based on the raytrace method (Thernisien et al., 2006, 2009)
- Each structure has a unique geometry (Hess & Zhang, 2014)
 - Ejecta- GCS
 - Sheath- Spheroid

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Processing the Images

- Different image processing techinques are used
- The front of the sheath can be best observed by using running difference images
- Ejecta boundary can be seen as a bright feature utilizing base ratio images
- The sheath can be seen well into the heliosphere, but as the ejecta propagates and expands, its density drops and becomes fainter



Drag-Based Model

CME measurements are then fit with Drag-Based Model (Vršnak et al., 2013)

$$egin{aligned} &a(t) = -\Gamma(v(t) - v_{sw}) |v(t) - v_{sw}| \ &v(t) = rac{v_0 - v_{sw}}{1 + \Gamma(v_0 - v_{sw})t} + v_{sw} \ &R(t) = rac{1}{\Gamma} / n [1 + \Gamma(v_0 - v_{sw})t] + v_{sw}t + R_0 \end{aligned}$$

Initial height (R_0) and velocity (v_0) can be determined reliably from the measurements. Upstream solar wind speed (v_{sw}) , ACE data is used for now. This leaves the drag parameter (Γ) as the only true unknown

Modifying the DBM

- Most work using the DBM uses static, fixed parameters
- Making some physical and geometric assumptions about the flux rope, we simplify the form of Γ given by Cargill (2004)

$$\Gamma = rac{c_d A
ho_{sw}}{M + M_v}
ightarrow \Gamma(R) = rac{c_d}{rac{
ho_0 \kappa R_0}{
ho_{sw0}} + rac{\kappa R}{2}}$$

 Using measurement and fittings, a height-dependent Γ can be determined, yielding an iterative drag model

$$R(t+1) = \frac{1}{\Gamma(R(t))} ln[1 + \Gamma(R(t))(v(t) - v_{sw})t] + v_{sw}t + R(t)$$

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Geometric Correction

- Initially Predictions for CMEs far from Sun-Earth line were consistently early
- CME curvature effect
- Using the GCS geometry (right) a height correction was determined as a function of the deviation angle (θ)



Geometric Correction Cont.

This led to an opposite effect with the GCS geometry causing late predictions, so a weighted average of the two is used



Fitting the Sheath Front



- The previous slides apply to the ejecta
- The method failed to predict the sheath
- By measuring both fronts, the standoff distance in the heliosphere can be known
- Combining the results of a SD fit with the flux rope model gives sheath height

Model Example



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Prediction Results

Results Table

ICME Date ^a	ΔT_{SF}^{b}	ΔT_{EJ}^{b}	ΔV_{SF}^{c}	ΔV_{EJ}^{c}	$\rho_{ratio}(R(0))^d$	$\rho_{ratio}(L1)^d$	$\rho_{ratio}(ACE)^e$
04/05/2010	1.89	0.38	23.3	26.4	32.17	0.91	0.41
05/24/2010	5.69	2.52	96.3	38.1	6.70	0.15	1.21
09/14/2011	6.68	4.39	15.8	13.0	3.24	0.09	0.71
07/12/2012	0.84	1.51	24.8	22.4	18.61	0.41	0.61
09/28/2012	0.34	0.9	61.6	45.6	10.31	0.31	0.97
10/27/2012	4.99	0.28	24.5	19.0	14.78	0.47	0.67
03/15/2013	3.91	0.26	22.9	7.2	5.98	0.21	0.38
Average	3.47	1.46	38.5	24.5	13.11	0.36	0.80
RMS	1.58	0.76	17.9	12.9	-	-	-

Table : a- The date of the ICME arrival at ACE

b- The absolute value of the difference in hours between the predicted and observed arrival of the sheath (SF) and Ejecta(EJ) c- The difference in velocity in km/s between the speed of each feature as predicted by the model and as compared to the average speed observed for each feature in-situ

d- The derived density ratio from the model at the initial height of observation and at the point where the ejecta reaches L1

e- The ratio of the densities of the ejecta and solar wind, as determined from the average values of each from ACE.

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Arrival Comparisons



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Velocity Comparisons



Comparison with Other Models



ICME Date	Our Model	ESAª	Static ^b	
			DBM	
04/05/2010	-1.9	-11.6	-14.0	
05/24/2010	-5.7	7.9	10.6	
09/14/2011	-6.7	-11.5	-6.0	
07/12/2012	0.8	17.4	2.9	
09/28/2012	-0.3	32.9	22.5	
10/27/2012	-5.0	-3.7	2.1	
03/15/2013	3.9	8.0	-1.4	
Abs. Average	3.5	13.3	8.5	
RMS	1.6	6.0	4.2	

a-Gopalswamy et al. (2013) b-Vršnak et al. (2014)

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Discussion

Constraining Γ



- To determine Γ in the model, fittings are perfomed to each subset of measurements
- The first fittings are to points (0:4), then (0:5) and so on
- This provides an average F value out to each point
- Due to the limited number of points and the high variability of Γ, there is often a lot of scatter to these Γ values
- These Γ values are still able to constrain the initial Γ, which is all we need to create our height-dependent Γ profile

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Constraining Γ II

- The Γ values scale to the initial density ratios, which range from 3-32
- To reasonably determine these initial density rations, a minimum of 5-6 points are needed
- We also test the sensitivity to initial conditions with a hypothetical CME, differing with varying initial denisty



CME Expansion and Density Evolution

- The evolution of CME density relative to the ambient is an important difference in our model
- A constant- Γ drag is based on assuming $ho \propto 1/r^2$
- This would be valid if CME only expanded with the solar wind and underwent no internal expansion
- Near the Sun, the CME is more dense than the solar wind, but by the time it reaches L1 it is less
- Therefore it stands to reason that the CME must undergo a more rapid drop in density

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CME Expansion and Density Evolution II

- CME Mass is conserved, so the controlling factor for denisty is the CME Expansion
- For expansion to be self-similar (GCS), the internal radial expansion would have to equal the lateral expansion in the solar wind
- $\bullet\,$ This would lead to $\rho \propto 1/r^3$
- However, we know CME self-similarity is an over-simplification that breaks down as the CME propagates

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Expansion



Riley & Crooker (2004)

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CME Expansion and Density Evolution III

- Our model is based on this r^{-3} dependence, leading to the 1/r term in Γ
- This model leads to densities that are too low relative to the ambient in-situ
- Based on our curvature analysis, we can estimate the lateral expansion is twice as large as the internal expansion
- This indicates that a density evolution on the order of $r^{-2.4}$ might be more physically accurate for the model



Limitations for Real-Time Operational Forecasting

- Real-time measurement
- Current Lack of STEREO
- Difficulty of Solar Wind Prediction
- Need to test for false positives

Weaknesses of the Model

- Multiple CME Interaction Events
- Lack of Magnetic Field Inputs
- The model is only as good as the measurements taken
- Possible Selection Bias

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The Advantages of the Model

- Instantaneous Model Calculation
- Maximum Lead Time
- With each piece of new data, new calculation can be run
- The full characteristcs of propagation between the Sun and the Earth can be determined

Planned Future Studies

- Testing model with less ideal data (Solar Wind models, realtime data, LASCO only etc.)
- Using White-Light images to estimate CME density near the Sun
- Comparison with other models, such Eruptive Flux Rope (EFR) model (right) (Chen, 1996) for magnetic field
- Better determination of physics of sheath front generation to improve that part of the model



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Improvements Based On Future Observations

- With Solar Orbiter and Solar Probe, we will be able to get both extra height and velocity measurements near the Sun
- We can also more accurately determine near Sun densities, which will allow us to include a more physically accurate density/expansion model



 For permanent stereoscopic imaging, a permanent L5 observer would be a great benefit to our tracking process

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Work with MHD Models



- We have done preliminary work with multiple MHD models
 - COIN-TVD (Shen et al., 2014)
 - ENLIL (Odstrčil & Pizzo, 1999)
- Cross-validation with numerical models allows us to test many physical aspects of our work
- We can also experiment with different inputs in the same model to see how things change
- We can compare visualizations of the MHD model data to real observations and measurement

Synthetic COIN-TVD Images



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ENLIL data from multiple viewpoints



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Effect of Longitude on ENLIL Visualizations



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Conclusions and Future Work

- Despite the obstacles, we demonstrate an effective proof of concept
- Our model can also lead to a better physical understanding of CME propagation
- We also demonstrate the importance of considering propagation deviation and considering the unique environment of each eruption
- Better physics/assumptions may still improve the model

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ISEST Wiki

- At George Mason, I have worked on the International Study of Earth Affecting Solar Transients (ISEST)
- ISEST is an international collaboration for studying geoeffective CMEs
- Anyone can see the progress of the program, as well as contributed data and a repository of events at the ISEST Wiki Site http://solar.gmu.edu/heliophysics
- Anyone can also create an account at this site and contribute their own commentary, data or events to the site

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Thank You

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